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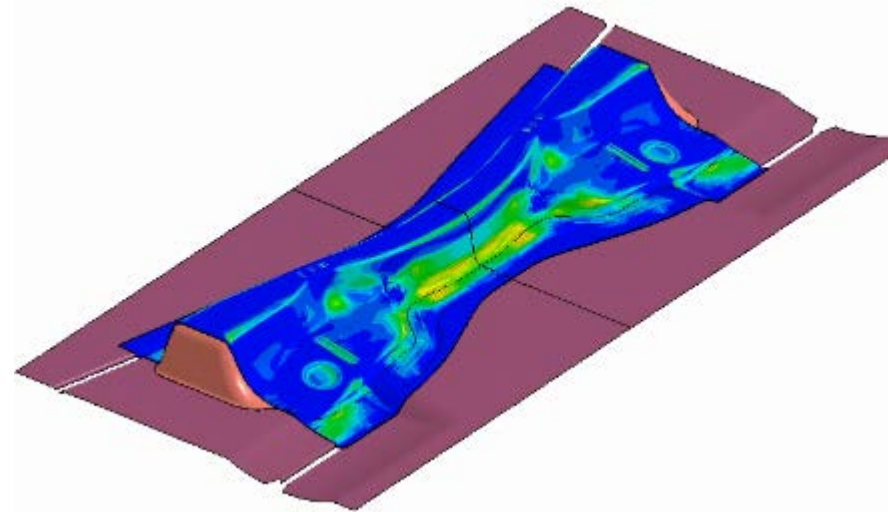
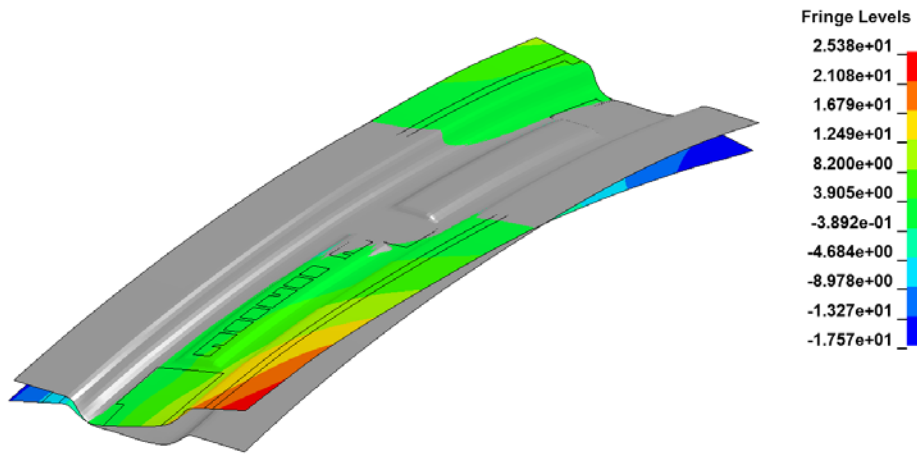
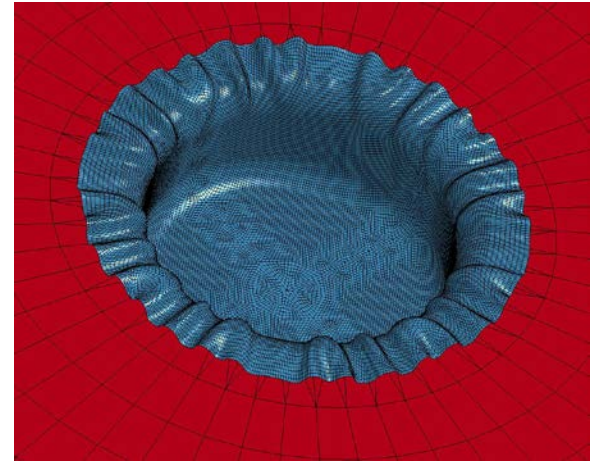


# Simulations of materials processing using LS-DYNA - A journey

Mikael Schill, Dynamore Nordic AB

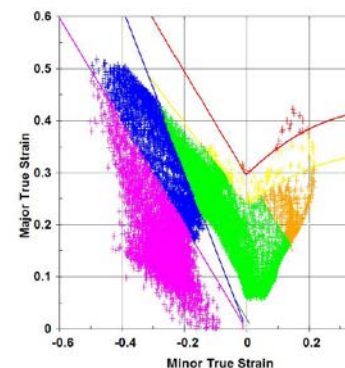
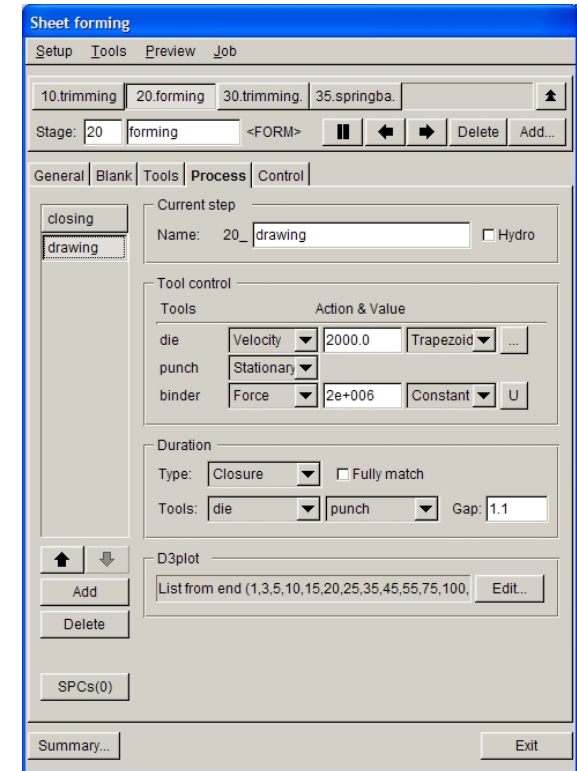
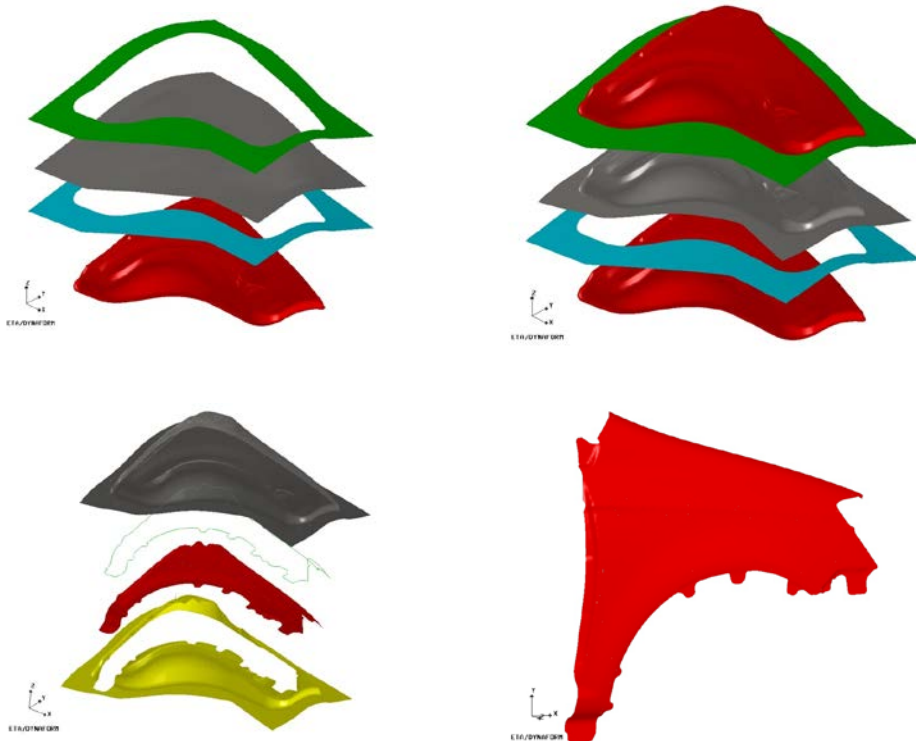
# First Step - Simulation of sheet metal forming

- Quasi static simulations of the deep drawing process
- Rigid tooling
- Predicting wrinkling, thickness, rupture, springback, blank geometry etc.



# Simulation of sheet metal forming

- Automated setup using tailored pre-processors
- Formability is evaluated through FLD diagram
- Automatic report generation
- Material databases are included

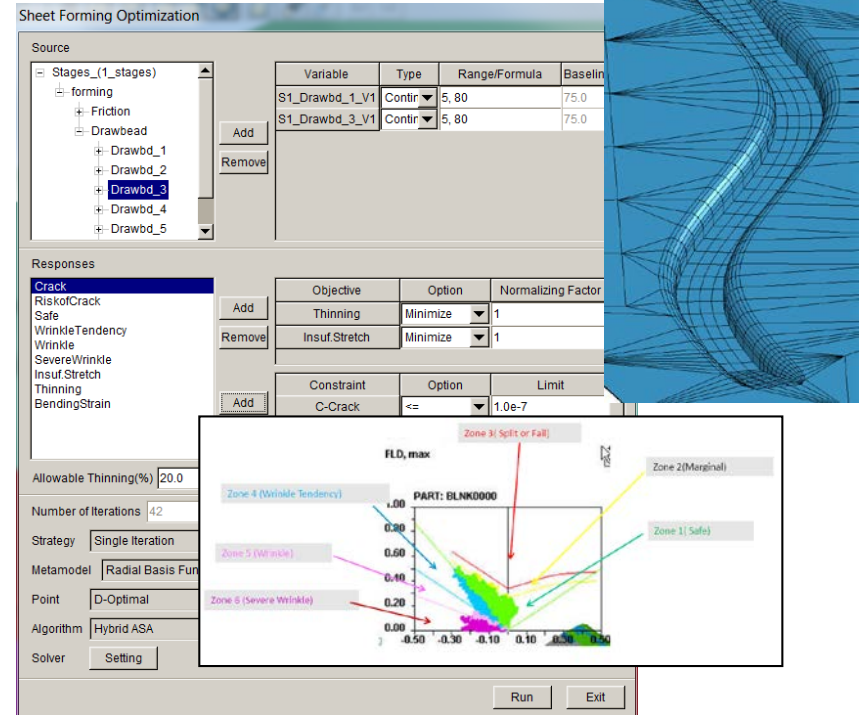
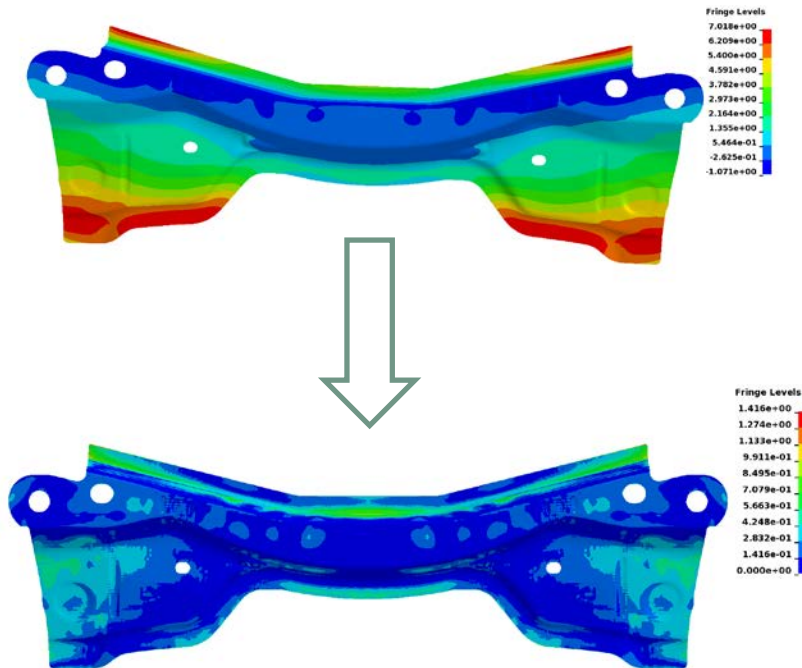


Formability key

Cracks	Red
Risk of cracks	Yellow
Severe thinning	Orange
Good	Green
Inadequate stretch	Grey
Wrinkling tendency	Blue
Wrinkles	Purple

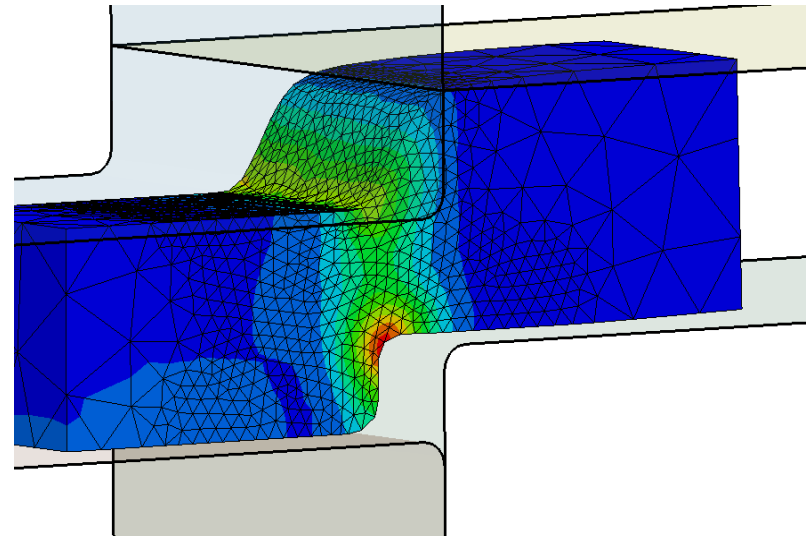
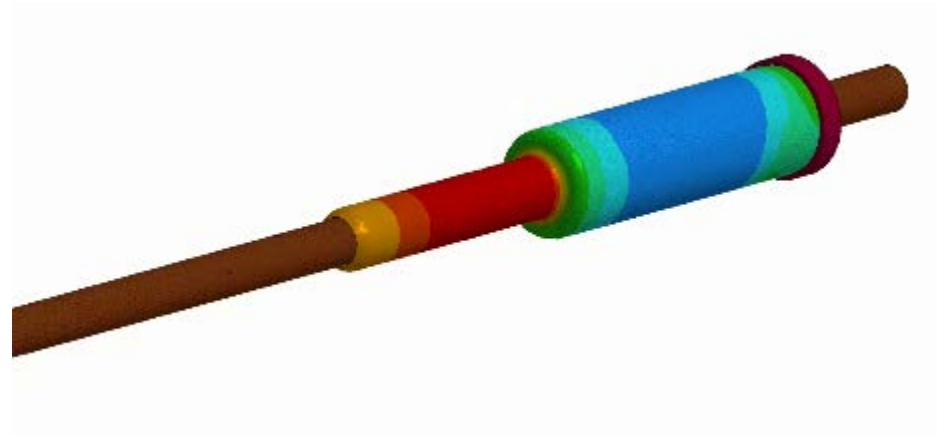
# Simulation of sheet metal forming

- Automatic optimization to find
  - Blank size geometry
  - Drawbead force and geometry
  - Springback compensated tools

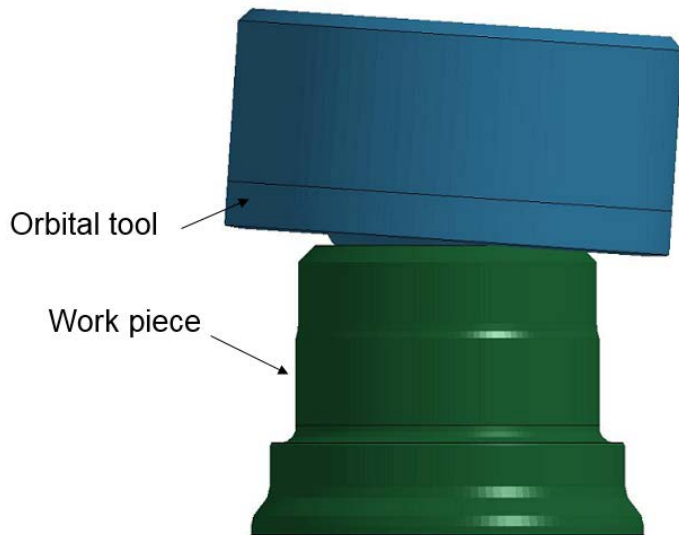
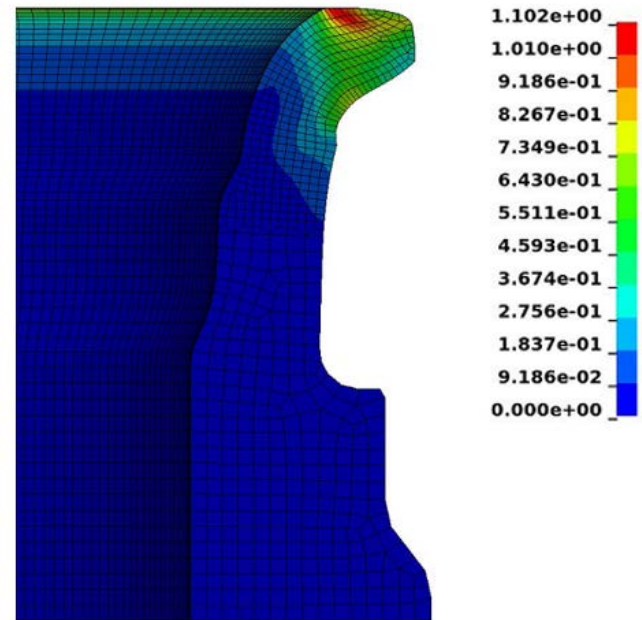
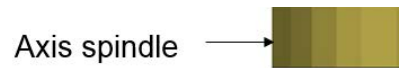
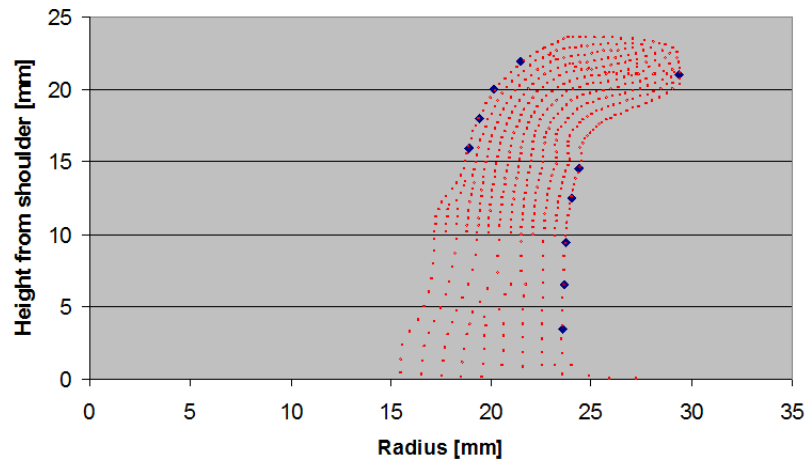


# Simulation of "bulk forming"

- Bulk forming is a generic term for forming processes with large deformations, e.g. ironing.
- Bulk forming typically involves (very) large deformations where distorted elements becomes an issue.
- In LS-DYNA there are several ways to deal with this problem.
  - Euler/Lagrange
  - 2D/3D Adaptivity
  - EFG/SPH meshless methods



# Bulk Forming - Orbital forming at SKF



11<sup>th</sup> European LS-DYNA Conference 2017, Salzburg, Austria

## Orbital forming of SKF's hub bearing units

Edin Omerspahic<sup>1</sup>, Johan Facht<sup>1</sup>, Anders Bernhardsson<sup>2</sup>

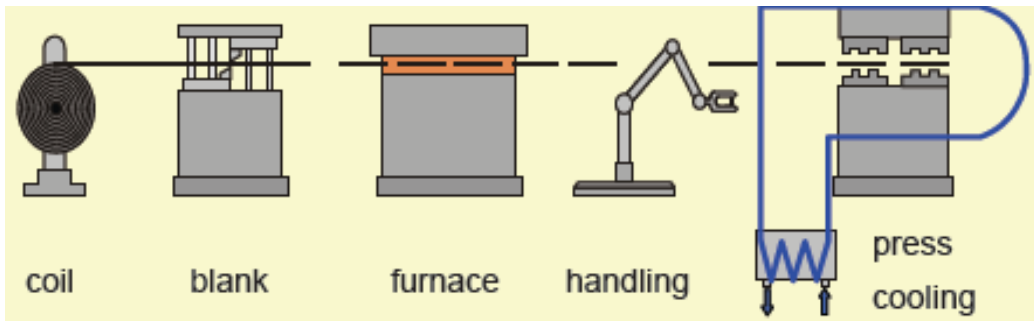
<sup>1</sup>Manufacturing Development Centre, AB SKF

<sup>2</sup>DYNAmore Nordic

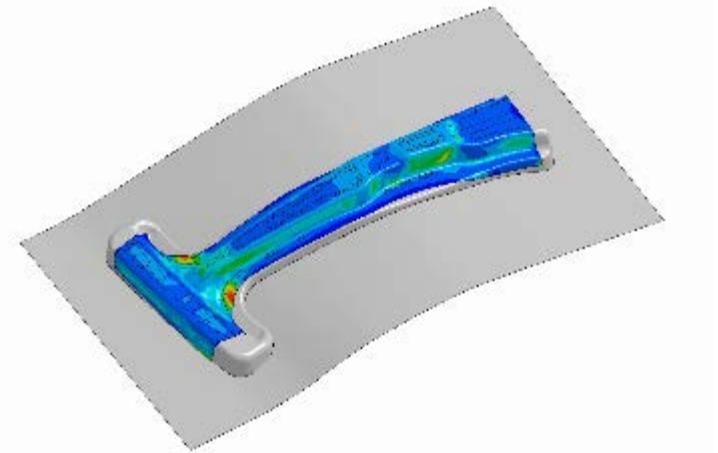
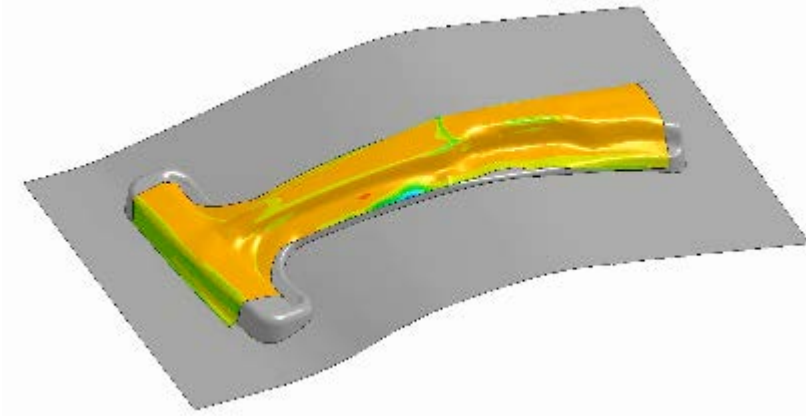


## Second step - Hot Stamping of Boron Steel

- Boron steel blanks are heated to austenite phase and then formed and subsequently cooled to form martensite

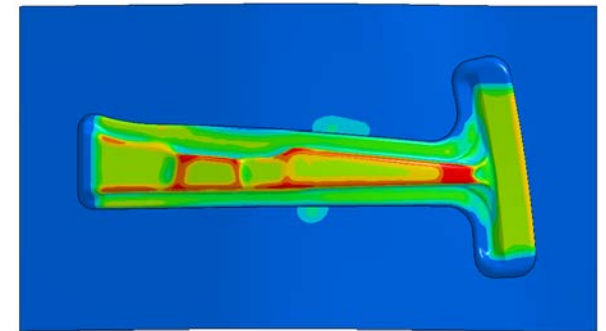
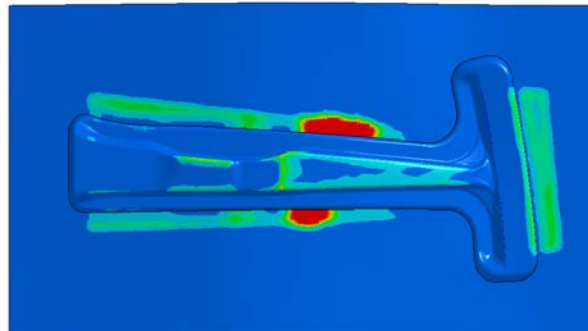
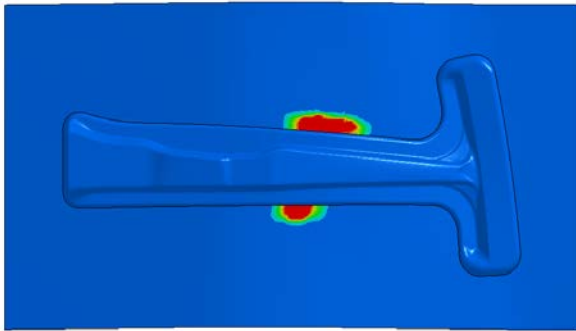
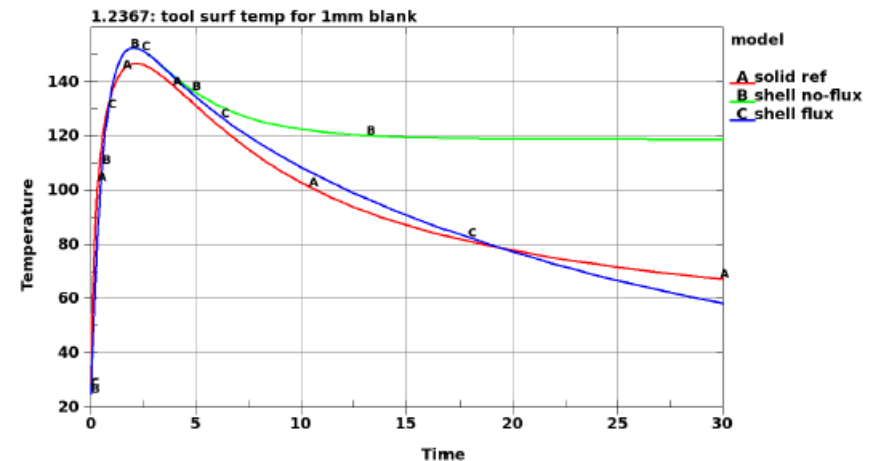
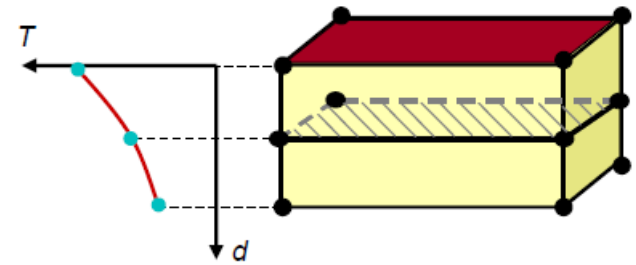


- Ultra High Strength Steel
- Extra High Strength Steel
- Very High Strength Steel
- High Strength Steel
- Mild Steel / Forming Grades
- Aluminium
- Magnesium



# Using thick shell elements in tooling

- By using thick thermal elements with appropriate boundary conditions and properties, it is possible to mimic the solid tooling temperatures using a shell element tool mesh.

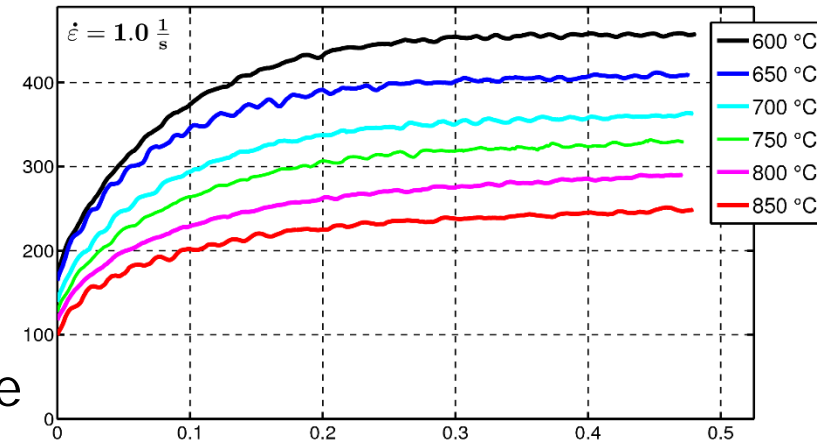




# Hot stamping with conventional simulation methods

## Capabilities

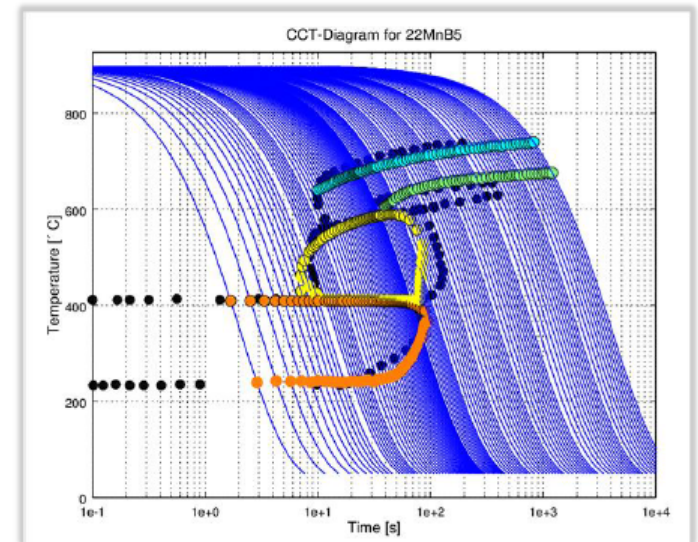
- correct prediction of forming in the austenitic state:
  - stresses and strains
  - thinning
  - forces
- prediction of temperature history in the blank/part



## Limits

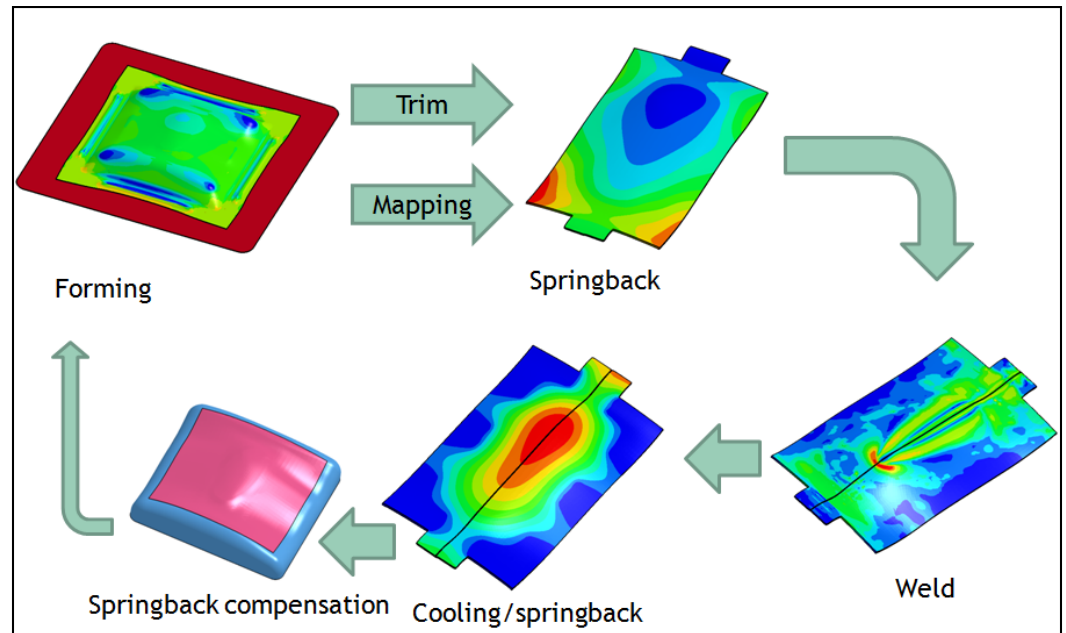
- prediction of microstructure (phase fractions) and hardness:
    - only rough estimations based on CCT diagram can be made
    - not possible for tailored tempering processes
- only rough estimations of final part properties like strength and hardness

- Based on the work by Åkerström and Bergman, Luleå.
- Material tailored for hot stamping / press hardening processes
  - Phase transition of austenite into ferrite, pearlite, bainite and martensite for cooling
  - Strain rate dependent thermo-elasto-plastic properties defined for individual phases
  - Transformation induced plasticity algorithm
  - Re-austenitization during heating
  - User input for microstructure computations is chemical composition alone
- Added:
  - Transformation induced strains
  - Welding functionality
  - Different transformation start temperatures for heating and for cooling



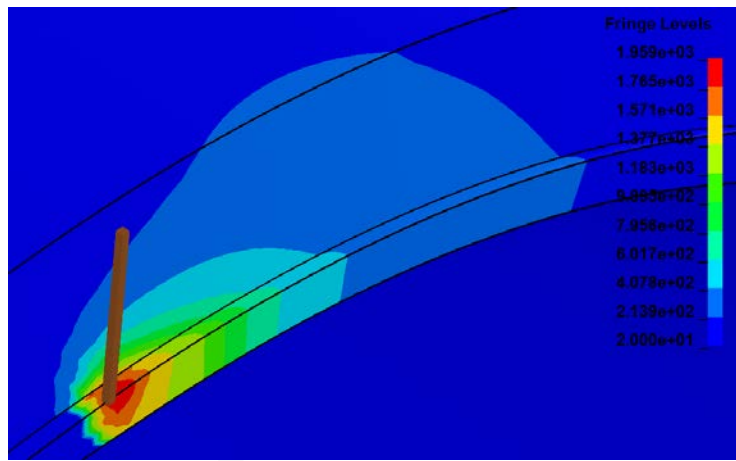
# Third step - Simulation of Welding

- Virtual process chain including Forming and Welding
- Using implicit/explicit solvers, mechanical and thermo-mechanical coupling and solid and shell elements.
- Novel material models, heat sources for welding and pre-processing GUI
- \*MAT\_244 is tailored for press-hardening and Boron steels and is not necessarily useful for welding
- New material model for welding processes and heat treatment - MAT\_254

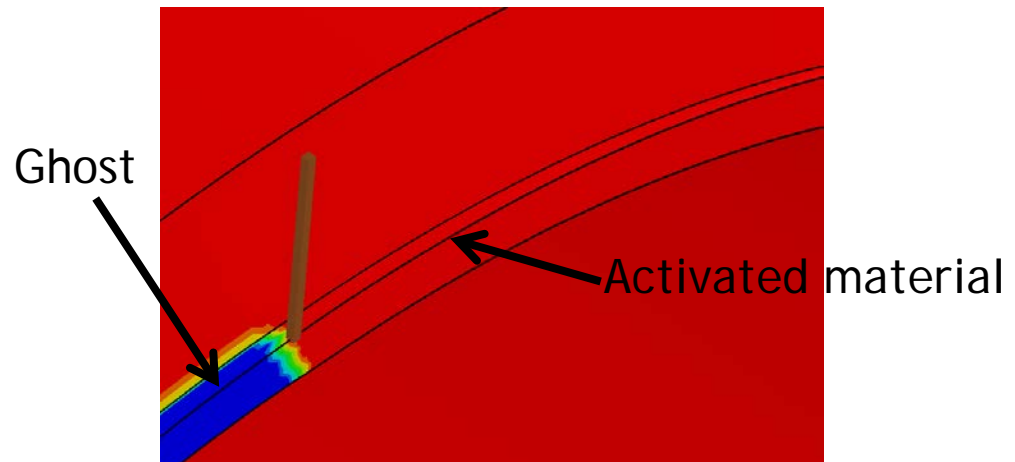


# Welding Simulations - \*MAT\_CWM

- The element can either be "solid", "Liquid" or "Ghost".
  - Solid: Material is activated in a previous weld pass
  - Liquid: Material will be activated in the current weld pass
  - Ghost: Material will not be activated in the current weld pass
- When the temperature reaches a specified temperature, material is activated and receives "material" properties.
- Apart from the ghost element function, the material model also includes Anneal functionality.
- Above the specified anneal temperature, all history variables such as hardening and back stress are set to zero.

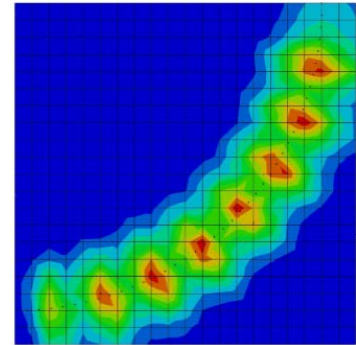


Temperature



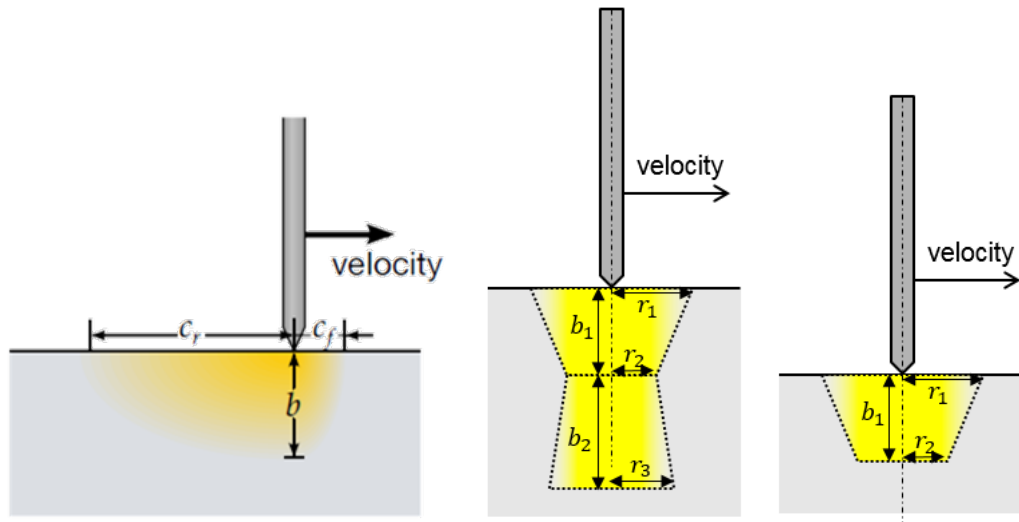
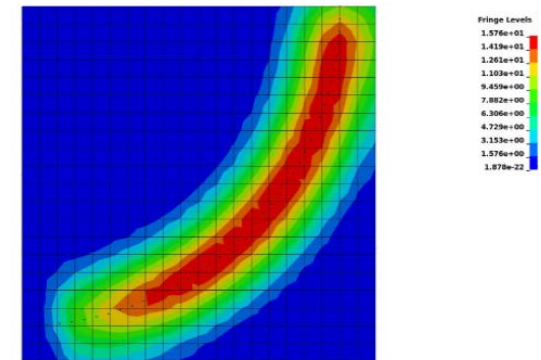
# Heat source

- Novel keyword \*BOUNDARY\_THERMAL\_WELD\_TRAJECTORY
- Heat source movement implemented in the thermal solver
- Heat source follows a node string defined in \*SET\_NODE
- Subcycling of the heat source
- User controlled integration for accurate heat input
- Goldak, cone and double cone heat sources



temperature field, NCYC = 1

temperature field, NCYC = 10



# Pre-processing - Welding plan

- By clicking the boxes, the welding order is determined.
- Possibility to add or remove stages.
- To each step, corresponding clamping and thermal boundary condition can be chosen.
- Double clicking on the rows opens the corresponding definitions.
- If the properties are defined, the box is coloured green.
- When the process is set up, an LS-DYNA input file is exported.
- The setup of the welding simulation can be saved/loaded from an ASCII file.

Sequence	Welds	Struct. B.C.	Therm. B.C.	
	1	2	3	4
== Welds ==				
6 Weld Pass 1				
8 Weld Pass 2				
Springback				
== Struct. B.C. ==				
2 edge x				
3 edge z				
4 edge2 z				
5 edge y				
6 sb xyz				
7 sb xz				
8 sb z				
== Therm. B.C. ==				
Air segm.				
1 Table				

Application Settings Help

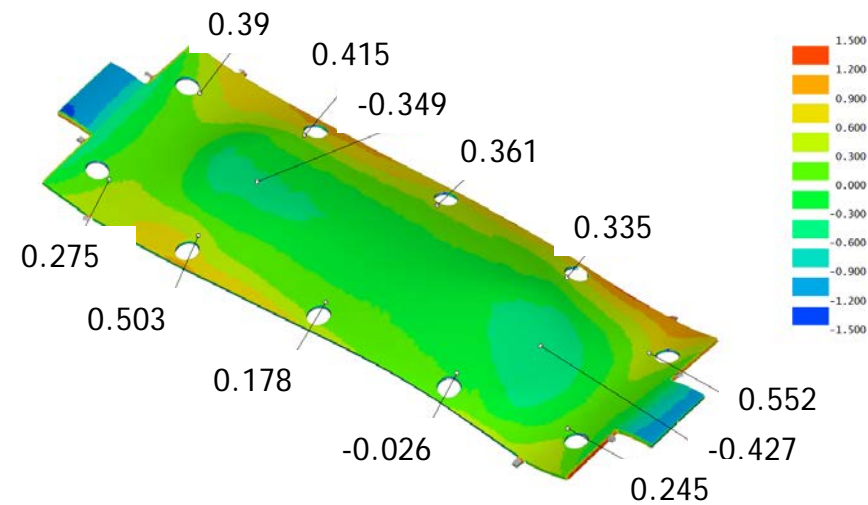
- Occupant Safety
- Metal Forming
- Model Checking
- Tools
  - Media
  - CurveGen
  - Integral
  - Welding Simulation
- Crash Safety
- NVH
- ALE Setup
- Granular Flow Setup
- 3DGraph
- Customize
- Segment Pressure Wave
- Wear

Load Save Export Browse

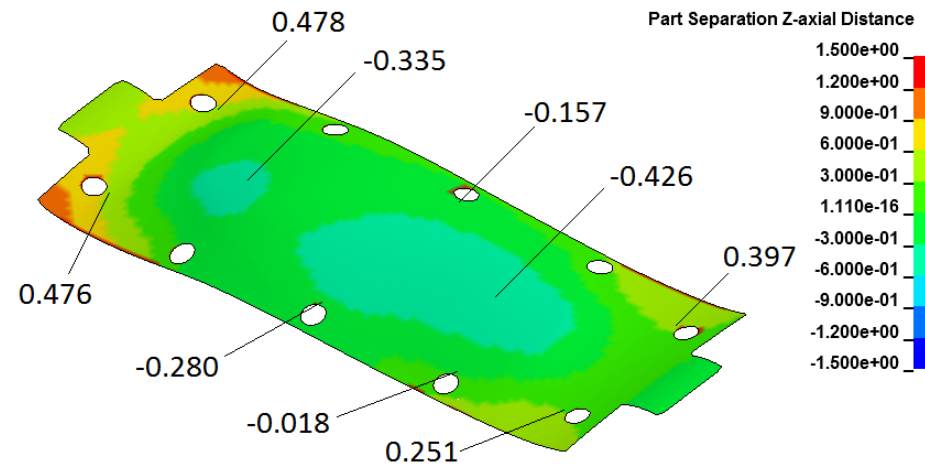


# Welding Example - Simulation results after forming

- The measured springback after forming are determined using a 3D scanning and best fit CAD evaluation method in a least square sense.



Measured



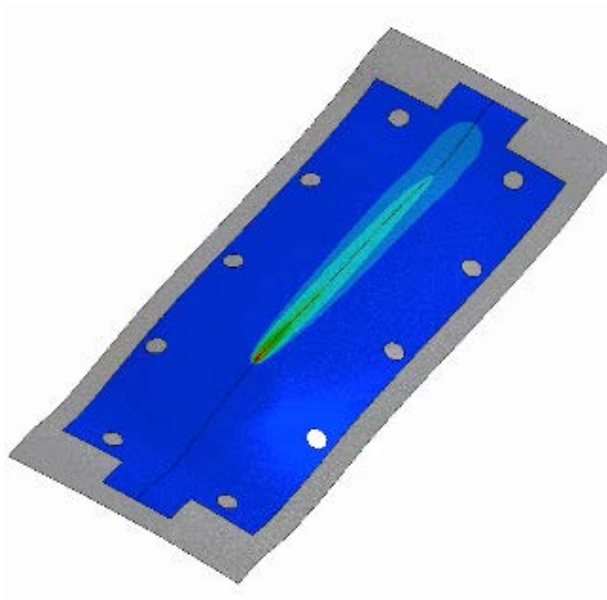
Simulated

Measured and predicted shape deviation after forming (mm).

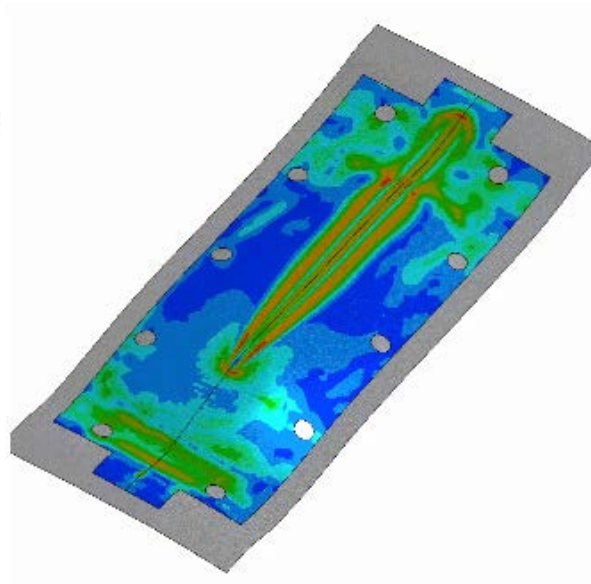
Lluís Pérez Caro, "Modelling of Forming and Welding in Alloy 718", Licentiate thesis, ISSN 1402-1757  
Luleå University of Technology, 2017

# Welding Example

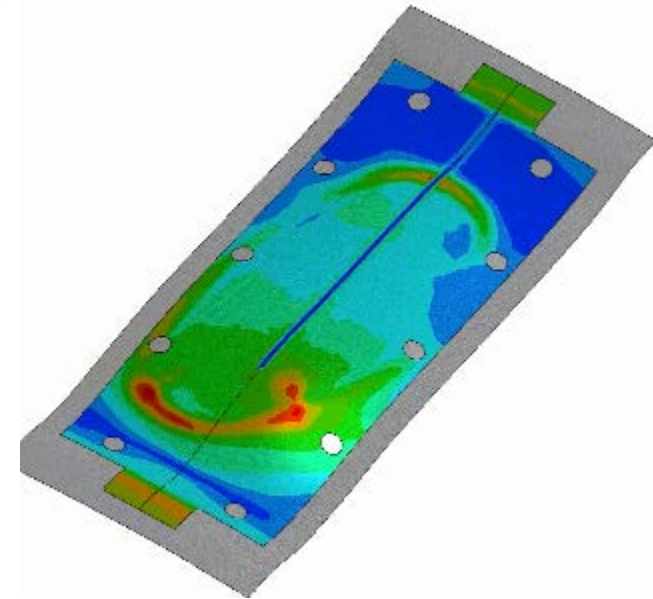
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Temperature



Stress

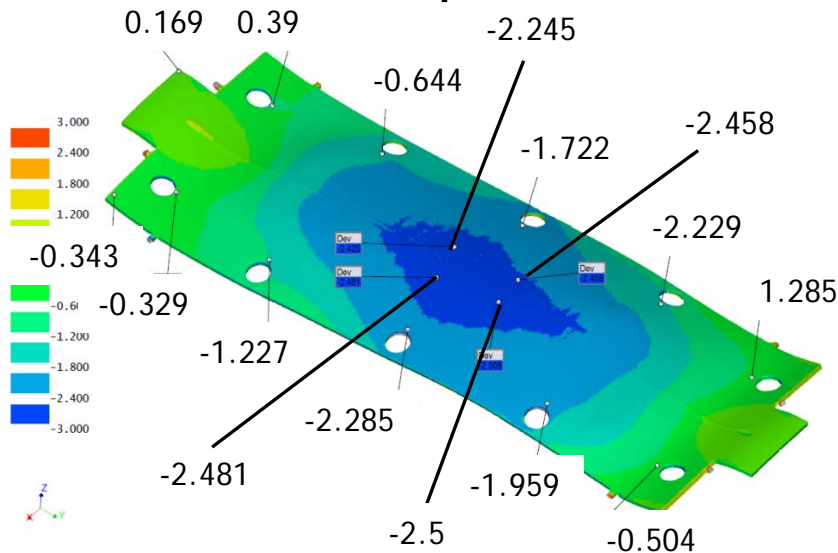


Effective plastic strain

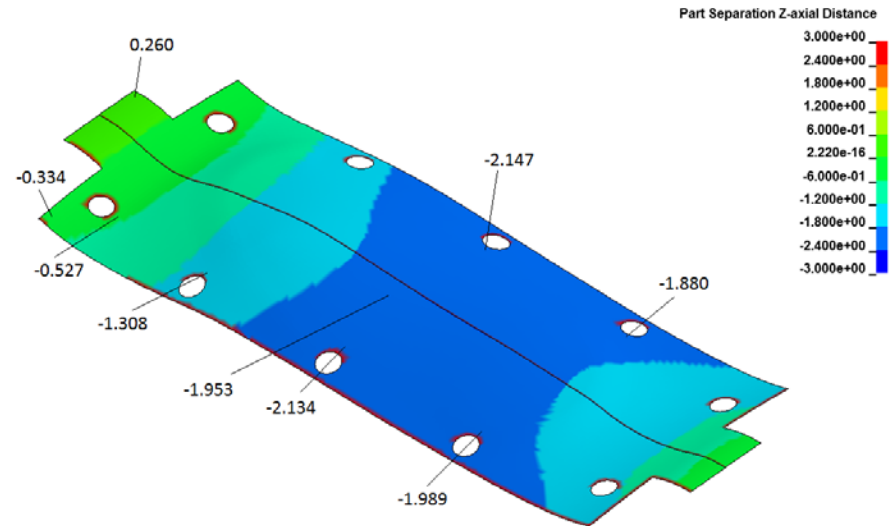
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Measured



Simulated

Measured and predicted shape deviation after welding (mm).

Lluís Pérez Caro, "Modelling of Forming and Welding in Alloy 718", Licentiate thesis, ISSN 1402-1757  
Luleå University of Technology, 2017

## Fourth step - \*MAT\_254 - Generalized phase change

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- New material formulation in LS-DYNA with:
  - Up to 24 individual phases
  - List of generic phase change mechanisms for each possible phase change in both cooling and heating
  - Material incorporates all features of \*MAT\_244
  - Phase change parameters are given in tables and are not computed by chemical composition
- Parameters of the material might come from a material database or a microstructure calculation
- Will be suitable for a wider range of steel alloys and aluminum alloys

# \*MAT\_254 - Generalized phase change

- JMAK
- Koistinen Marburger
- Kirkaldy
- Oddy
- ..

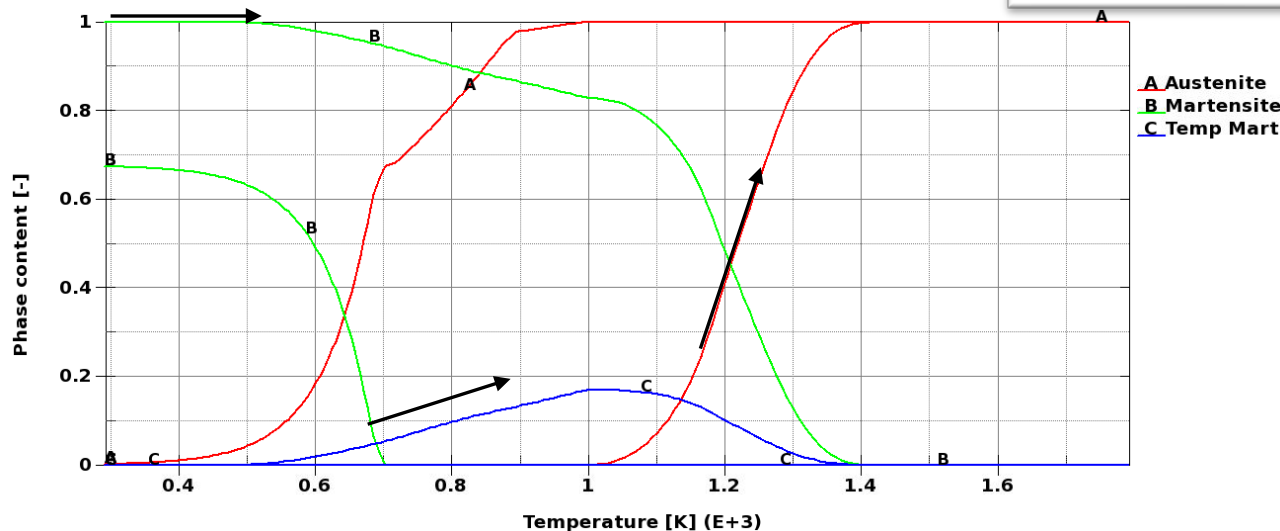
$$\frac{dx_b}{dt} = n(T)(k_{ab}x_a - k'_{ab}x_b) \left( \ln \left( \frac{k_{ab}(x_a + x_b)}{k_{ab}x_a - k'_{ab}x_b} \right) \right)^{\frac{n(T)-1.0}{n(T)}}$$

$$k_{ab} = \frac{x_{eq}(T)}{\tau(T)} f(\dot{T}), k'_{ab} = \frac{1.0 - x_{eq}(T)}{\tau(T)} f'(\dot{T})$$

$$x_b = x_a(1.0 - e^{-\alpha(T_{start}-T)})$$

$$\frac{dX_b}{dt} = 2^{0.5(G-1)} f(C) (T_{start} - T)^{n\tau} D(T) \frac{X_b^{n_1(1.0-X_b)} (1.0 - X_b)^{n_2X_b}}{Y(X_b)}, x_b = X_b x_{eq}(T)$$

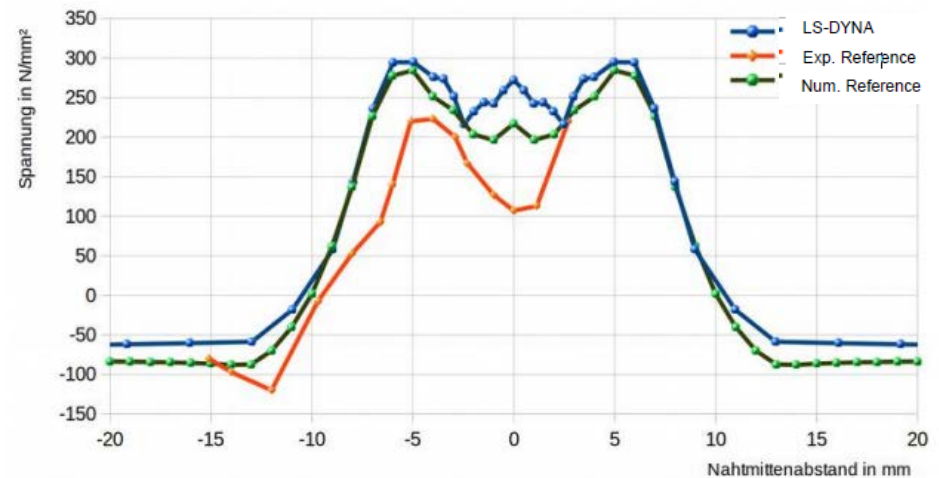
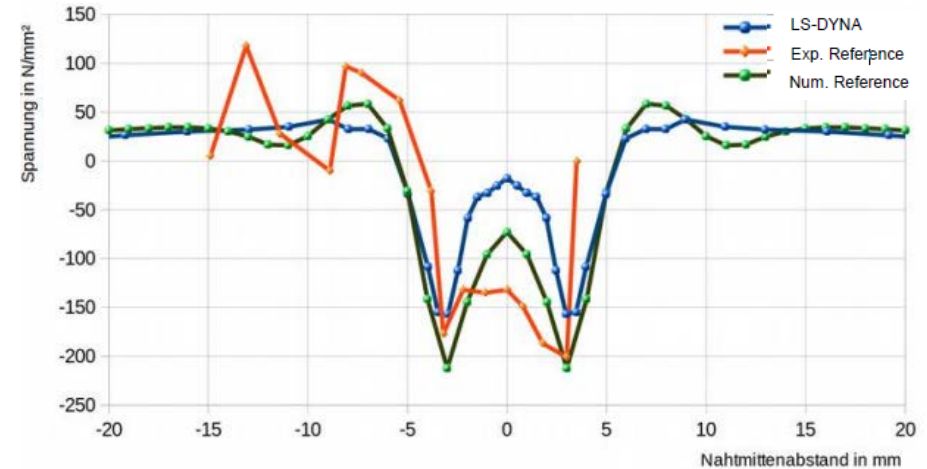
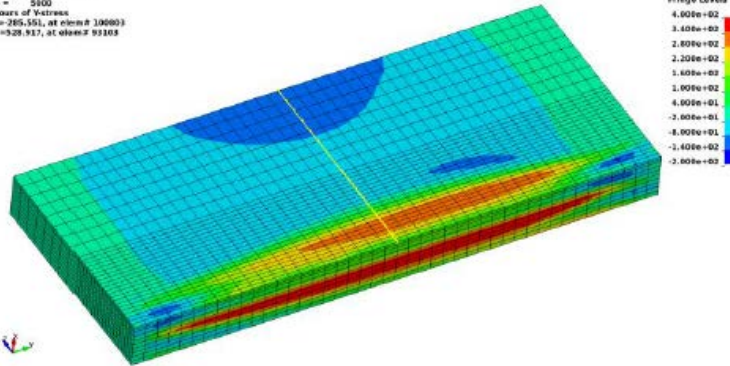
$$\frac{dx_b}{dt} = n \cdot \frac{x_a}{c_1(T - T_{start})^{-c_2}} \cdot \left( \ln \left( \frac{(x_a + x_b)}{x_a} \right) \right)^{\frac{n-1.0}{n}}$$



# Residual stresses with \*MAT\_254

## ■ Nitschke-Pagel test

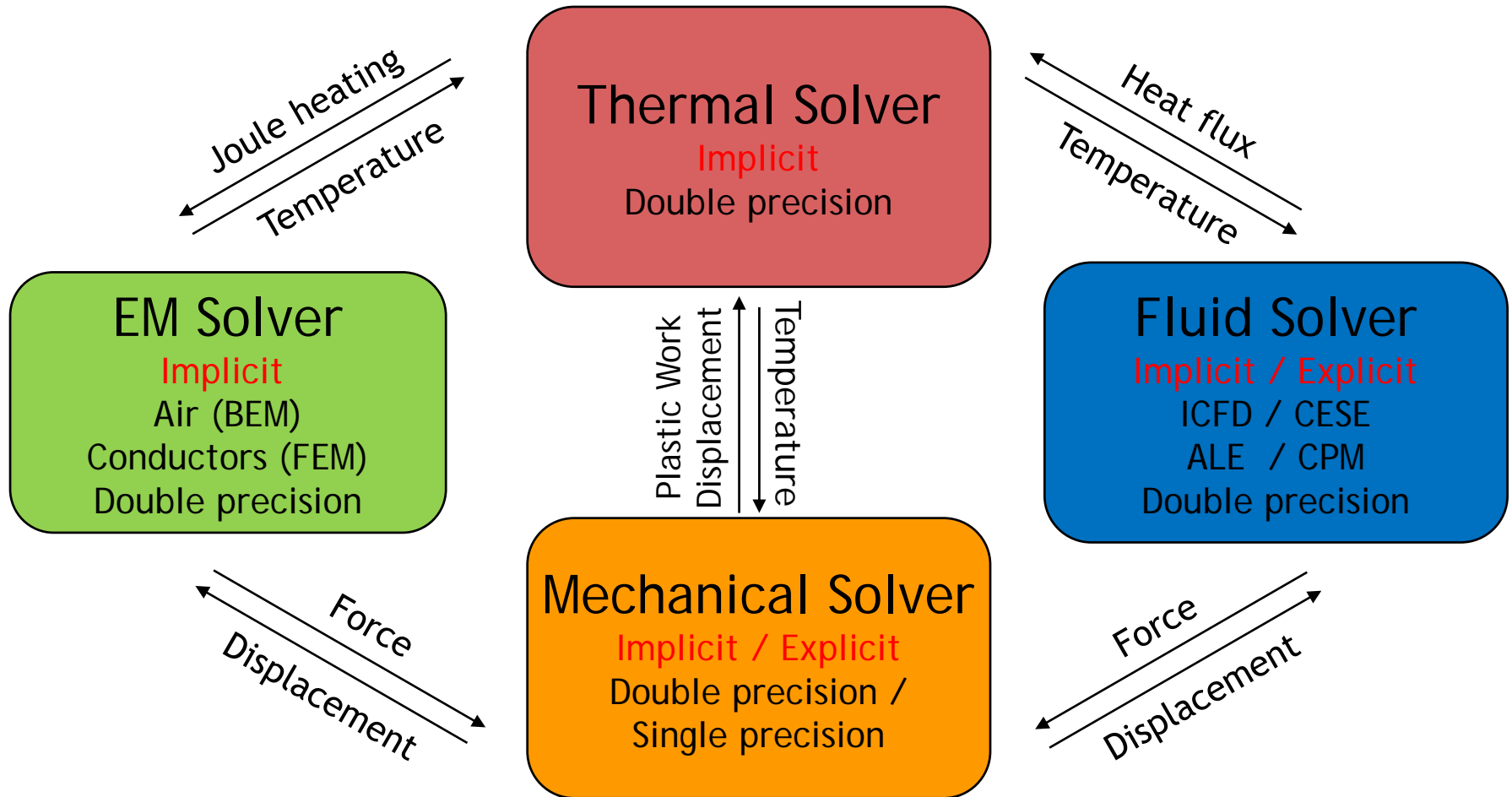
LS-DYNA user input  
Time = 0.00  
Contours of Vstress  
min=-285.551, at elem 8 100803  
max=928.517, at elem 2 93108



Loose, T.: Einfluß des transienten Schweißvorganges auf Verzug, Eigenspannungen und Stabilitätsverhalten axial gedrückter Kreiszylinderschalen aus Stahl, Diss, Karlsruhe, 2008

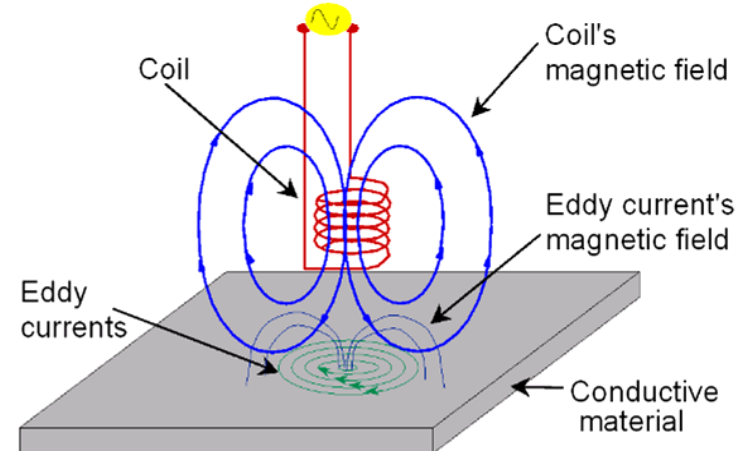


## Fifth step - Going into multiphysics

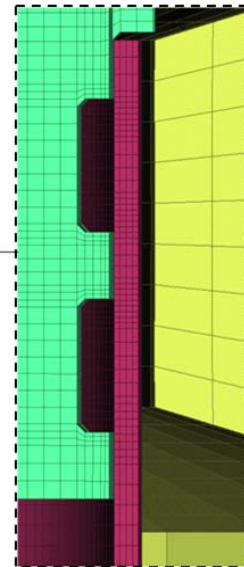
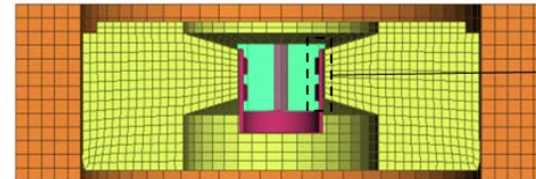


# Coupling with the electromagnetics solver

- Electromagnetic solver coupled with the mechanical and thermal solver
- LS-DYNA solves the EMF problem using a FEM+BEM method.
  - The Maxwell equations for the solid conductors are solved with FEM
  - The Maxwell equations for the insulators and air are solved with BEM
- Advantages with BEM:
  - No air mesh is needed and thus avoids meshing problems such as:
    - Mesh around complex conductors.
    - Re-mesh of air surrounding moving conductors.
    - Mesh in small gaps between conductors.
    - It does not need introduction of boundary infinite boundary condition

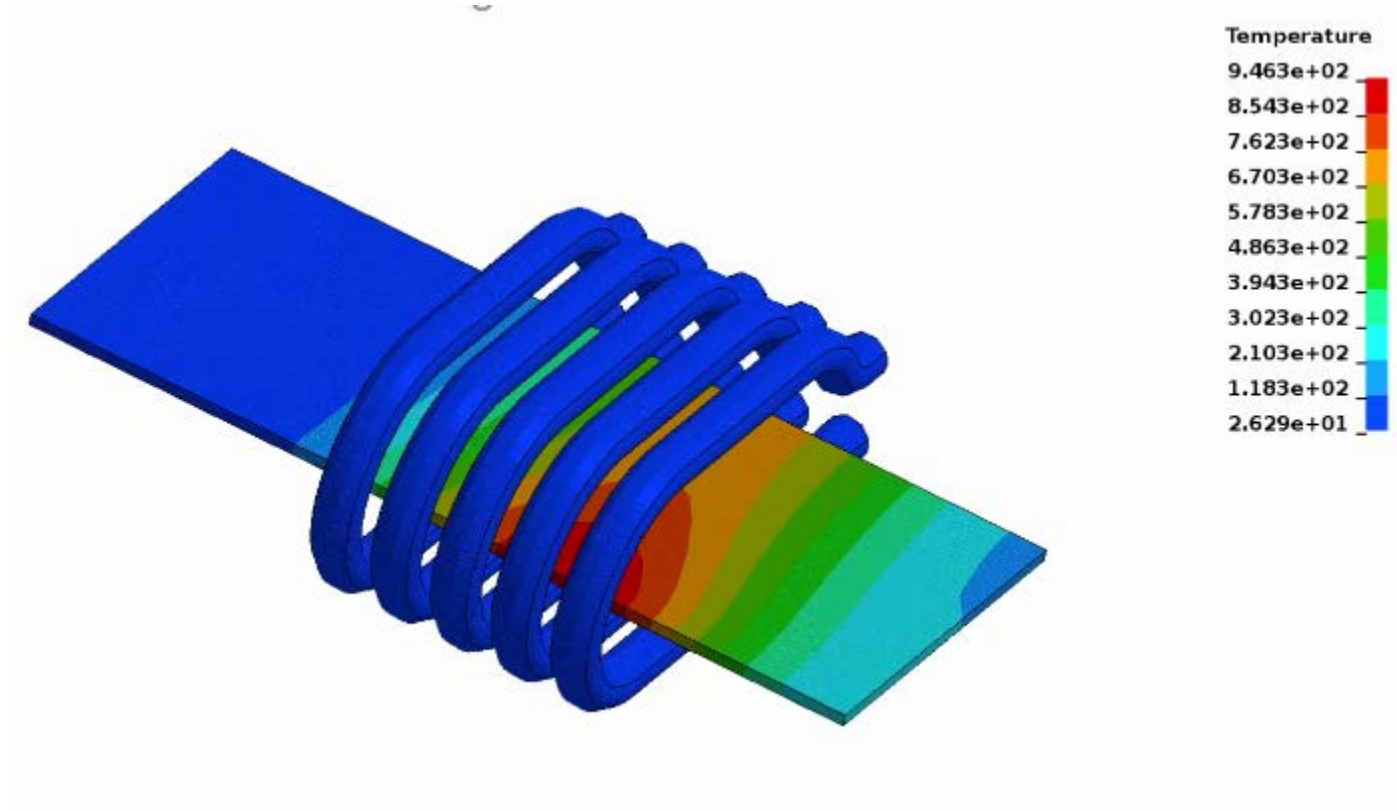


Courtesy of SAPA Technology

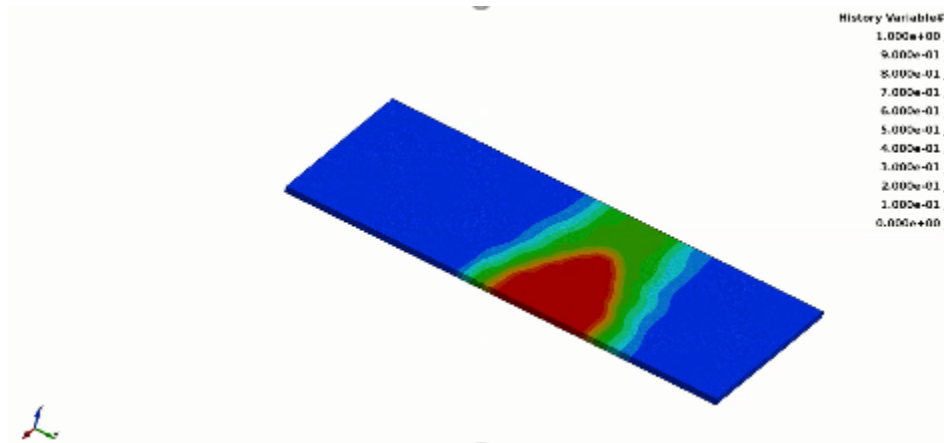


# Coupling with the electromagnetics solver

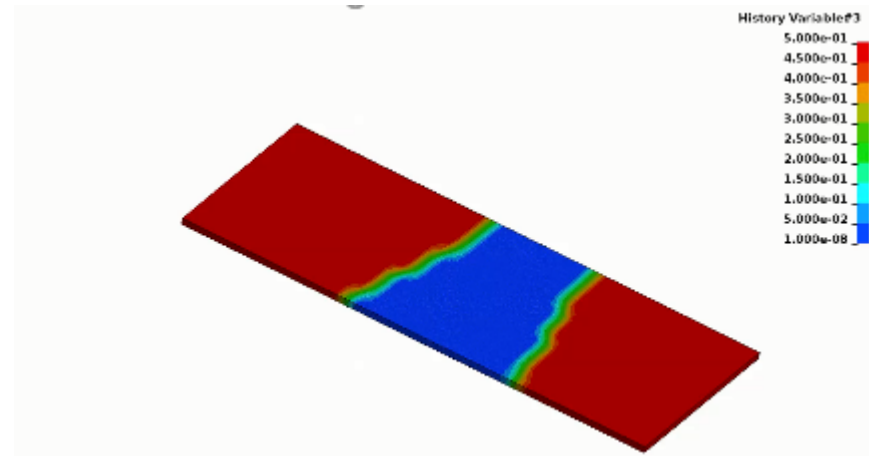
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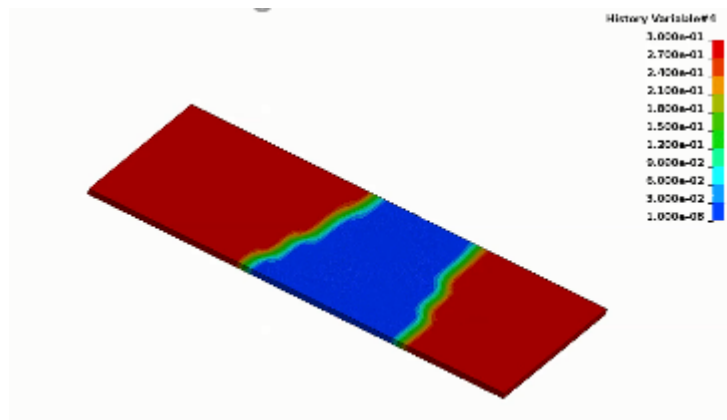
# Coupling with the electromagnetics solver



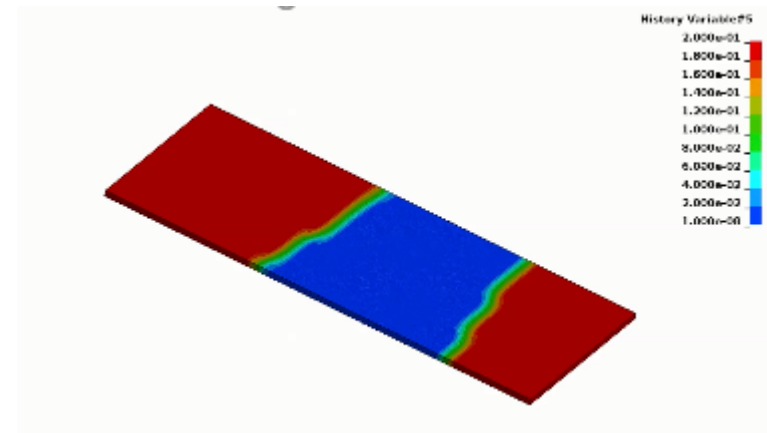
Austenite



Pearlite



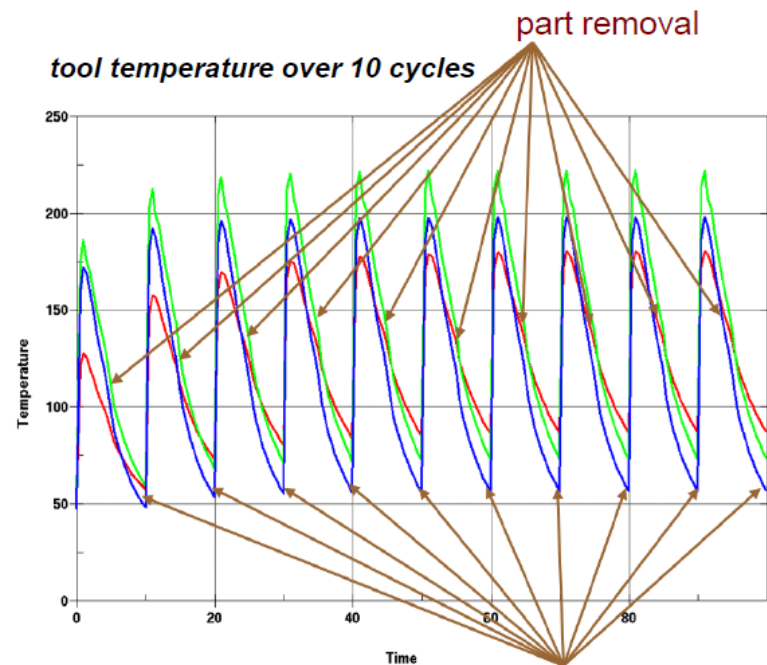
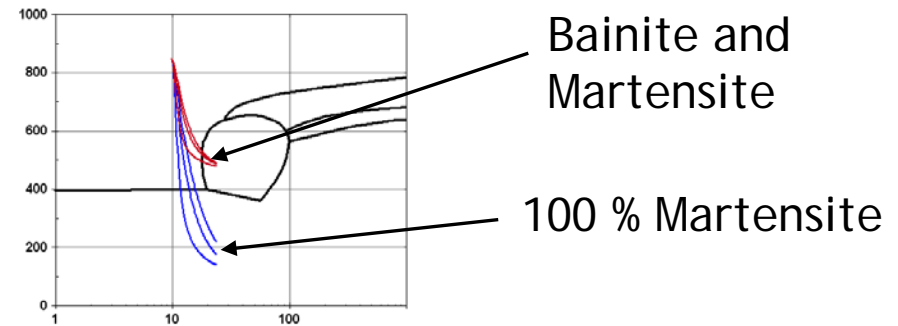
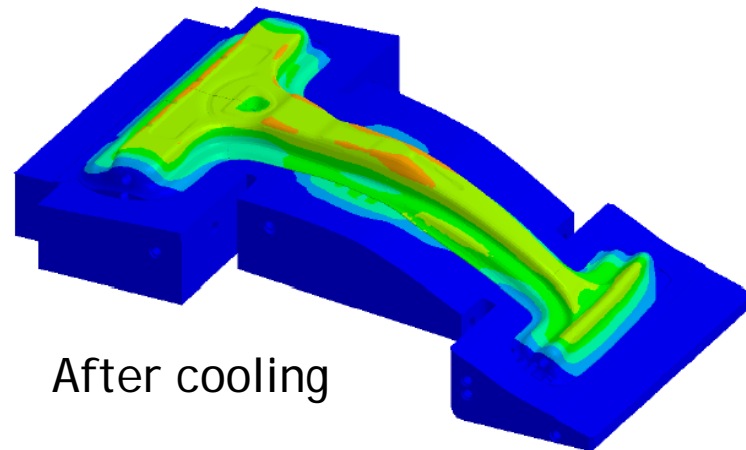
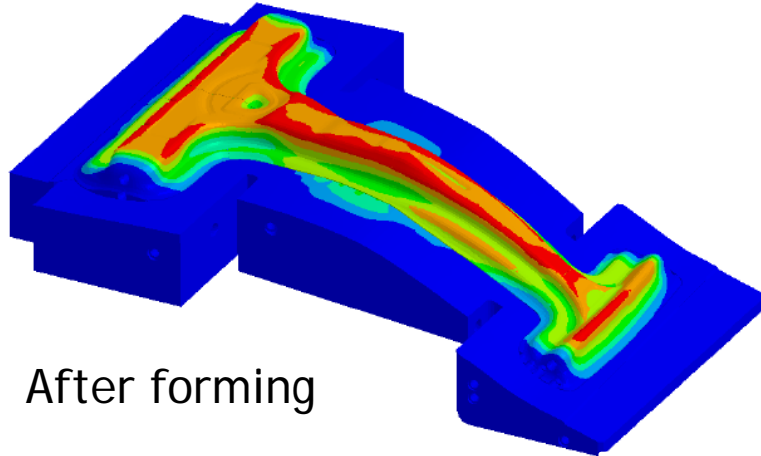
Bainite



Martensite

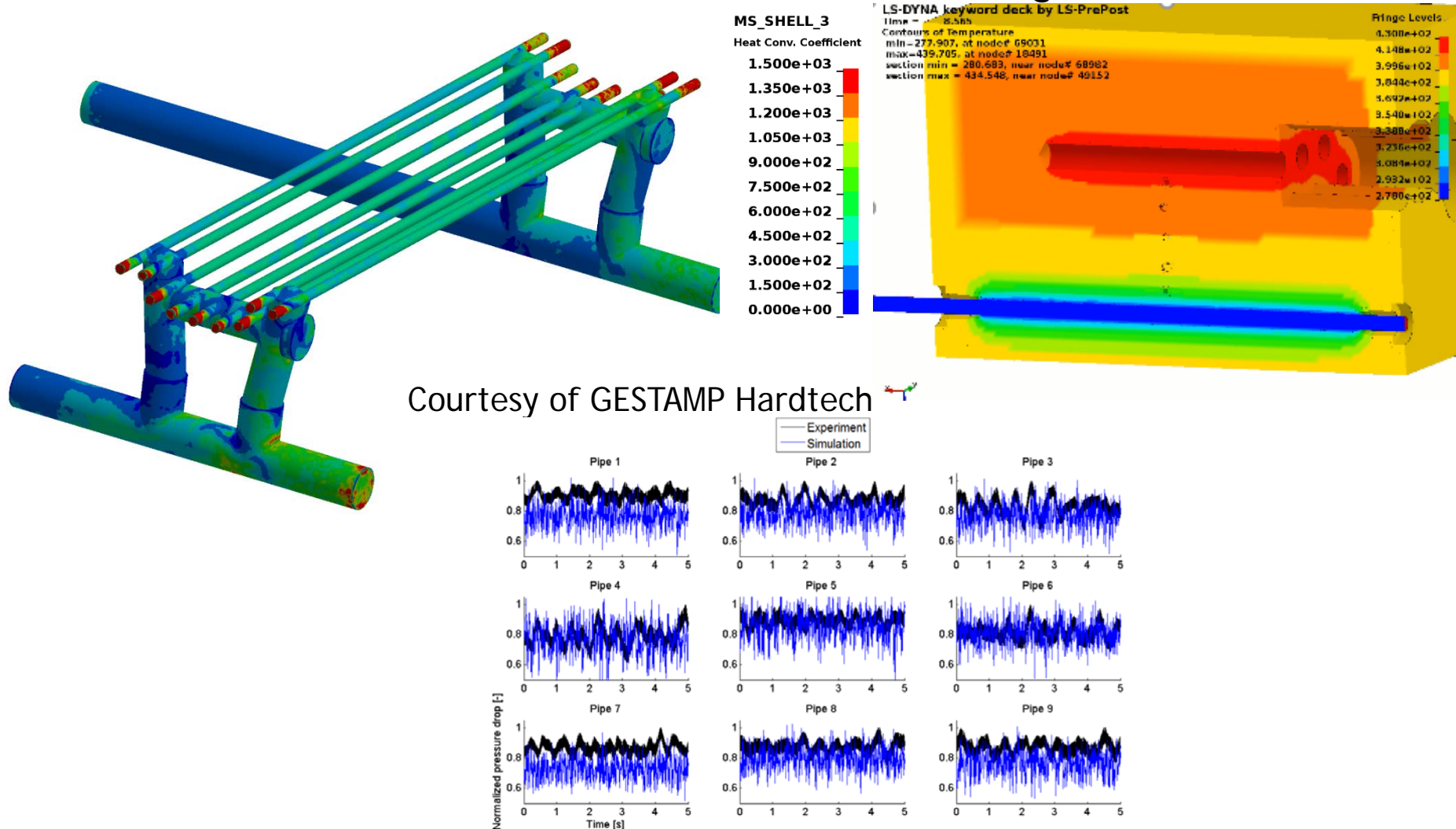
# Coupling with the ICFD solver

- Cycled hardening simulations identifies hot spots in tooling.



# Cooling channel simulation - CFD

- Determine heat transfer coefficients using CFD





# Summary

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- Simulation of the virtual process chain will involve
  - Different physical fields
  - Different type of solvers
  - Different resolution
  - Different descriptions
- Simulation of the virtual process chain involves moving the material properties through the simulations ensuring that the complete history of the material is predicted.
- The simulations need to be solved in a coupled manner where the different solvers communicate within the same code
- The solvers need to be scalable over several cores in order to run the simulations in a reasonable timeframe.

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Thank you!

